E2E TESTS for **AUTONOMOUS DRIVING** SOFTWARE

TIER IV

Born in China, Lived in NZ for 15 years, moved to Japan 3 years ago, currently living in Hokkaido



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- Father of a 10 month old boy





- Born in China, Lived in NZ for 15 years, moved to Japan 3 years ago, currently living in Hokkaido
- Father of a 10 month old boy
- Organising Tokyo Test Fest a QA conference in Tokyo, Japan.
 Catered for Japanese and English speakers

TIERIV

 Work at TIER IV - Autonomous Driving company based on Open Source Software

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- We develop autonomous driving software for
 - Buses
 - Robo Taxis
 - Factory carriers

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- We also develop web apps to support the above
 - Fleet management
 - In House CICD services
 - etc.

Contents

- Web Teams at an Autonomous Driving company
- The problem
- Our solution
- Why Cypress

WEB TEAMS @ an **AUTONOMOUS DRIVING** COMPANY

We provide autonomous driving platform adaptable for multiple applications







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AUTOWARE

Open Source Software



Pilot.Auto

TIER IV

 Autonomous Driving software development









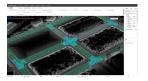


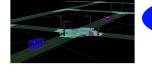
Web.Auto Overview





Management and execution of AD software build, scenario suites, maps and test results in a scalable cloud environment









Deployment

Operation

SIMULATION







DATA MANAGEMENT

Streamline upload and management of log and sensor data



Collection

REMOTE OPERATION

Vehicle Data

Remote monitoring and assistance

Driving

Firmware Images



FLEET MANAGEMENT

Scenario based, log based and digital twin simulations

Management and operation of AD vehicles, data analysis and OTA updates



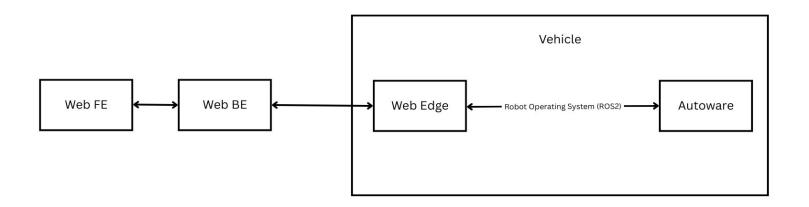
Traditional Web Apps

- Frontend
- Backend

Traditional Web Apps

- Frontend
- Backend
- Edge
 - Relays information between backend and Autoware

TIER IV Web Apps



TIER IV's web team's testing pyramid \(\)

E2E (with Autoware)

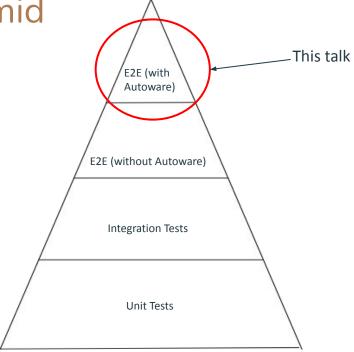
E2E (without Autoware)

Integration Tests

Unit Tests

TIER IV's web team's

testing pyramid

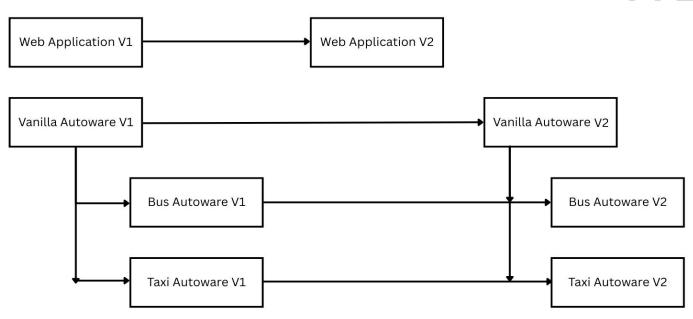


THE PROBLEM:

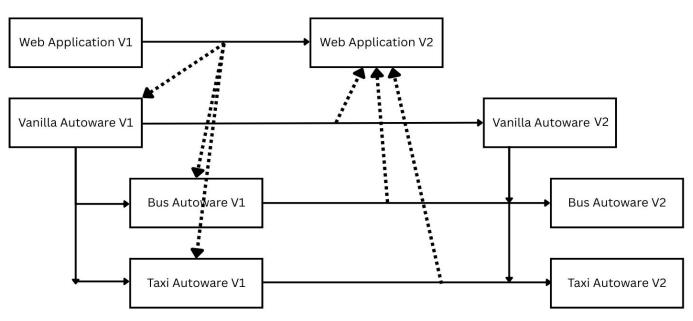
Asynchronous release cycles

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Web Application V1 Vanilla Autoware V1 Bus Autoware V1 Taxi Autoware V1







The Problem

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 Asynchronous releases require too much manual testing to make sure everything works properly



The Problem

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- So we need to automate



The Problem

- Asynchronous releases require too much manual testing to make sure everything works properly
- So we need to automate
- But the environment is so hard to prepare...
 - Autoware is a big ROS application that takes sometimes hours to build

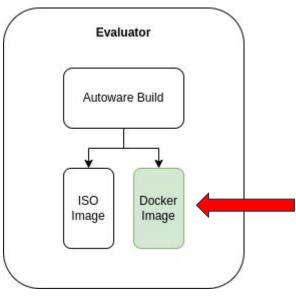


In comes our CICD service - Evaluator

- Pilot.Auto teams use this to build and test their Autoware
- It leaves ISO and Docker images as artifacts!

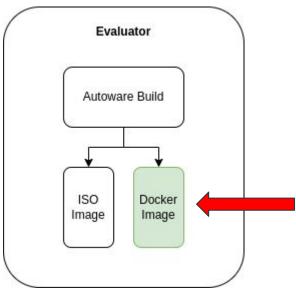
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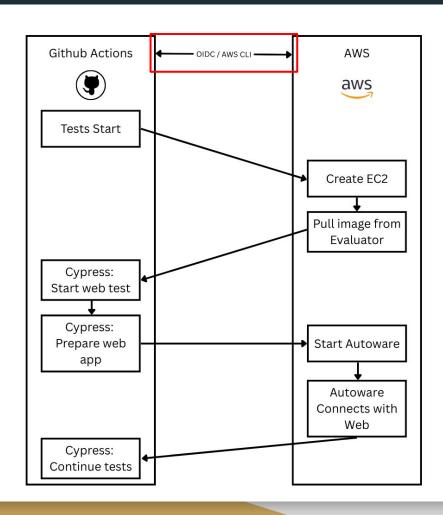
In comes our CICD service - Evaluator

- Pilot.Auto teams use this to build and test their Autoware
- It leaves ISO and Docker images as artifacts!
- Run images on AWS = problems solved!

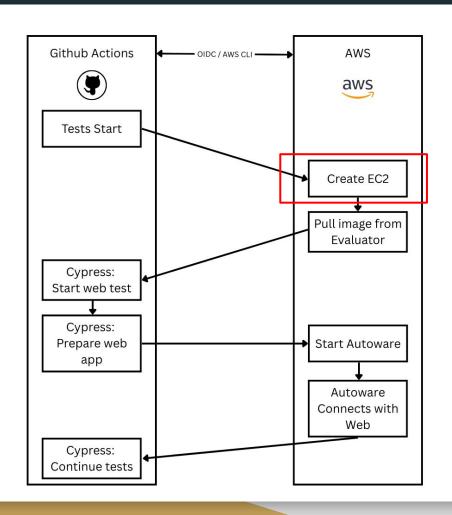


The Solution

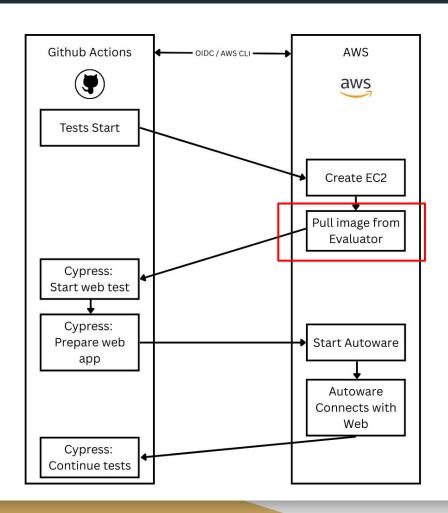
- We use OIDC to allow GitHub
 Actions to assume an IAM
 role for secure authentication
 with AWS
- AWS CLI from actions for all operations to AWS



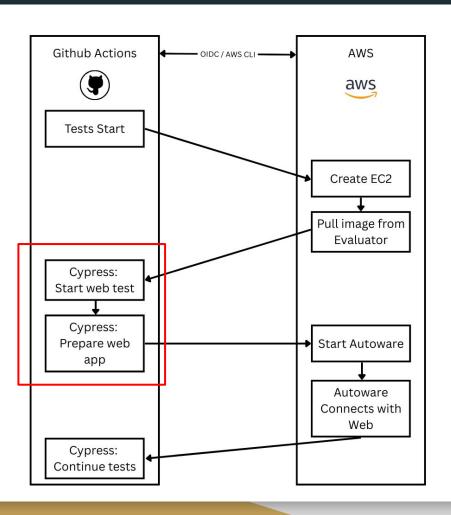
 We use AMI images so that the same EC2 environment is created every run



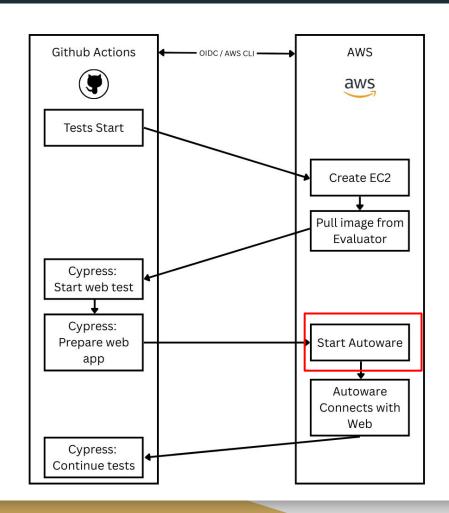
- Image is pulled with Evaluator's dev team's cli tool
- Image is slightly modified with a docker file to make it have the correct configurations to connect to the web
 - Systemd configurations etc.



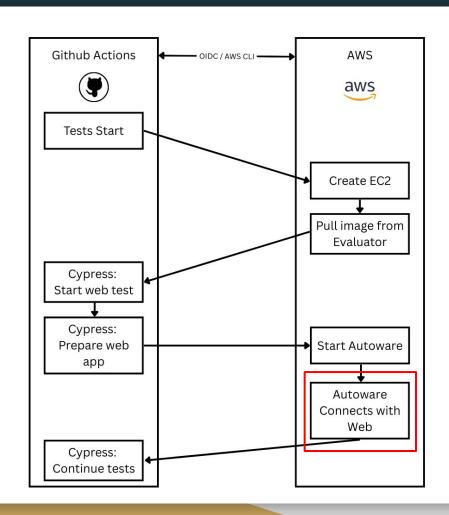
Example: register a
 vehicle on the web side
 and create a schedule,
 and make vehicle run
 on that schedule

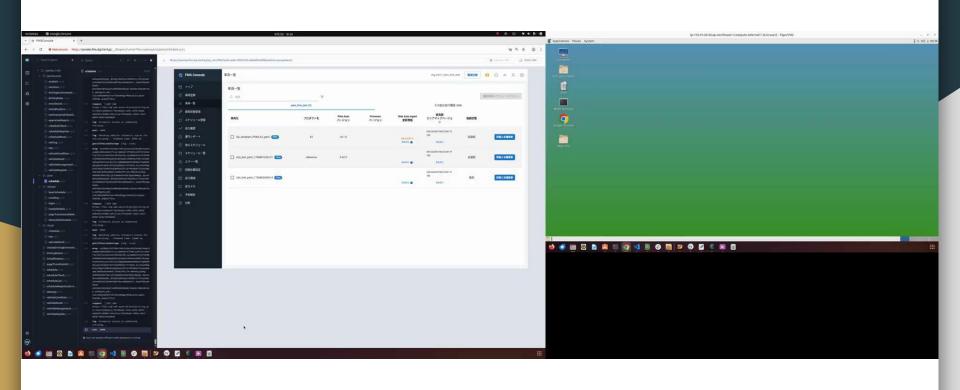


cy.exec -> ssh ->execute commandinside dockercontainer



 Connection with the help of AWS Greengrass (not part of the test but the application)







- Test replay on Cypress Cloud



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 - With complicated tests that needs to sync with aws Autoware, it's crucial to be able to debug failures efficiently



- Test replay on Cypress Cloud
- Access to node environment with cy.exec()



- Test replay on Cypress Cloud
- Access to node environment with cy.exec()
- Developer friendly for cross team collaboration

Q&A